

The Polyglot Cloud Native Debugger - Going Beyond APM

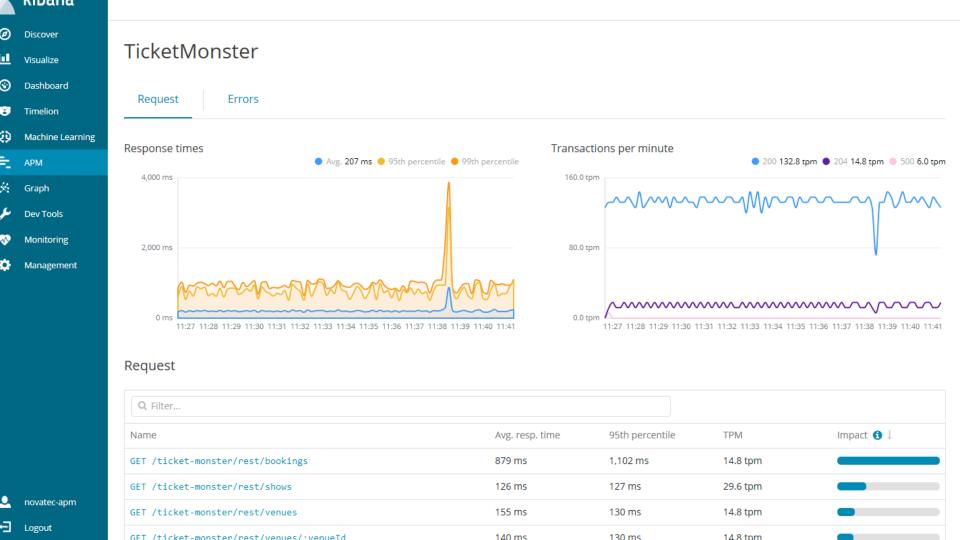
Shai Almog January 2022



```
Speaker ShaiAlmog = Speaker.builder()
  .withRoles(
      createDeveloperAdvocateAt("Lightrun"),
      createCoFounderAt("Codename One"))
  .withProfessionalExperience(30, TimeUnit.YEARS)
  .withTopCompanies("Sun", "Oracle", "Codename One", "Lightrun")
  .withTwitter("twitter.com/debugagent")
  .withBlog("talktotheduck.dev")
  .withEmail("shaia@lightrun.com")
  .withGitHub("github.com/shai-almog")
  .build();
```

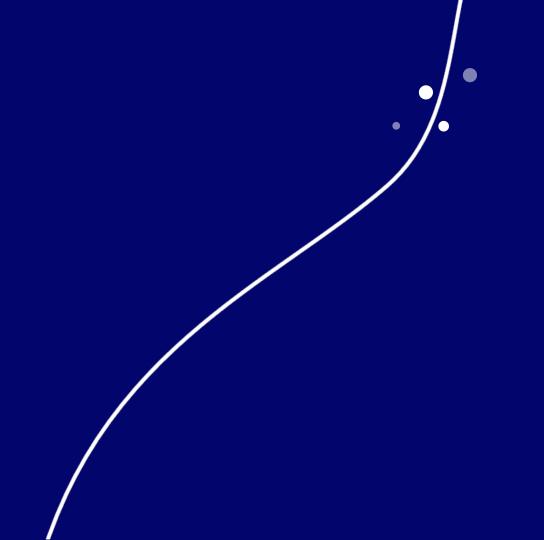












Lightrun



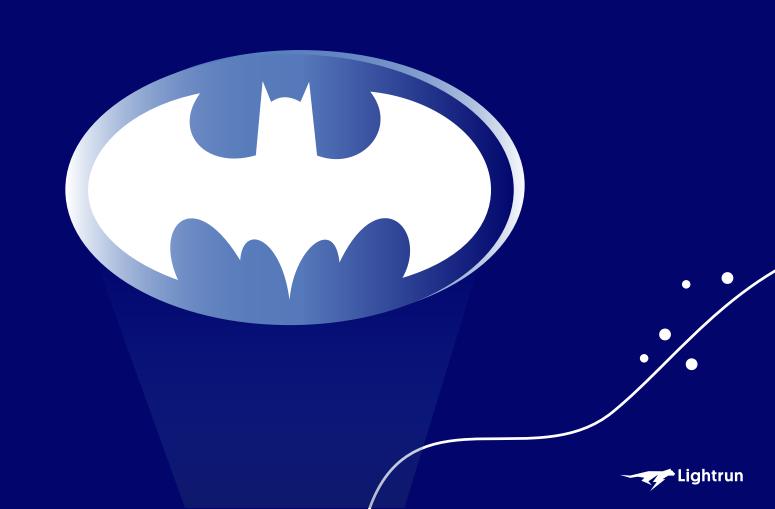
DevOps





DevOps



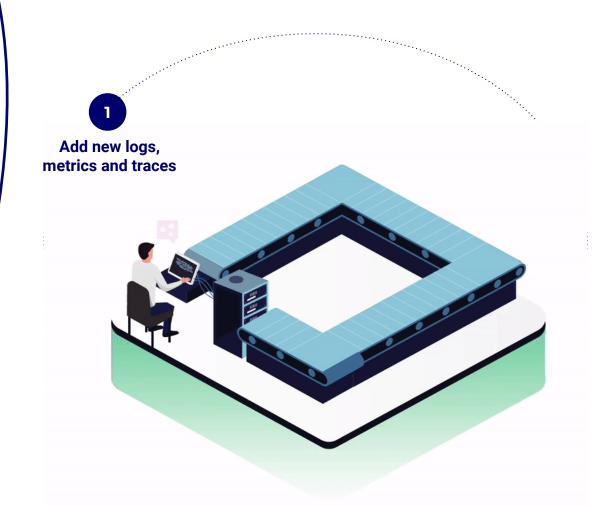


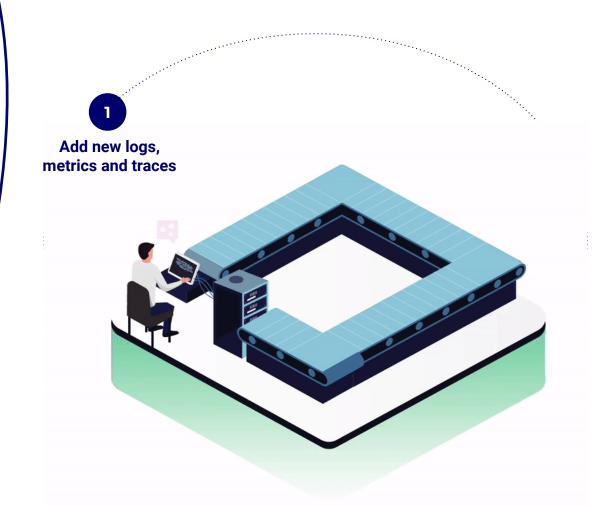


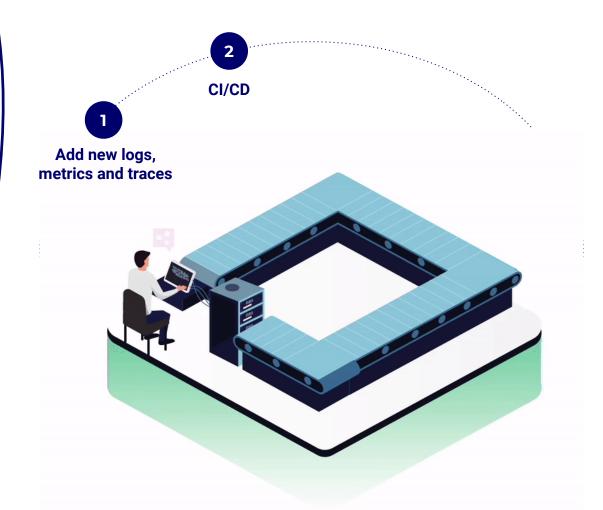


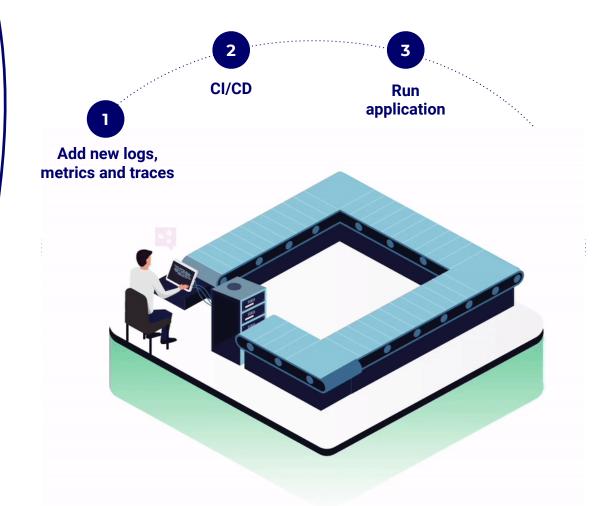
The Needle isn't Necessarily Here

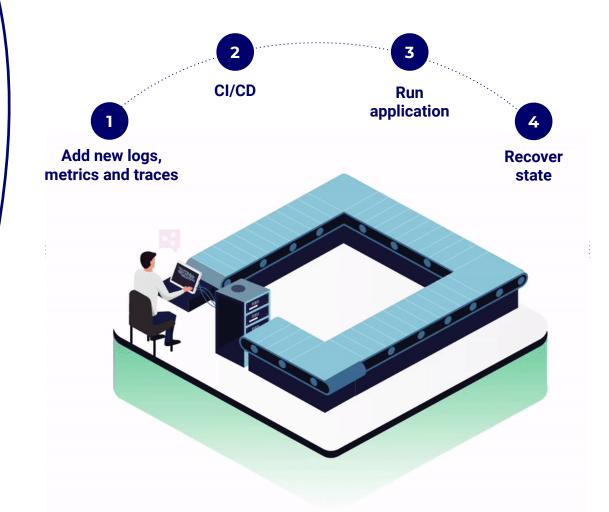












There has to be a Better Way!



We don't know what we'll run into



If Only we Could Debug...



But Debuggers aren't the Right Tool



They Can't Cross Server Boundaries



They can't handle Different Languages







Why Do APMs Impact Performance?



This isn't Too Bad

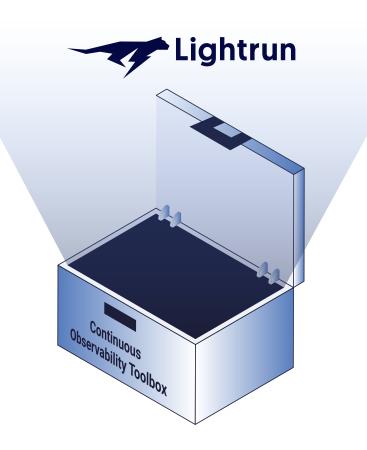




DevOps



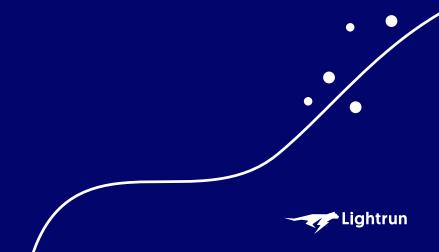
Production Debugging



Continuous Observability?



Continuous Observability?

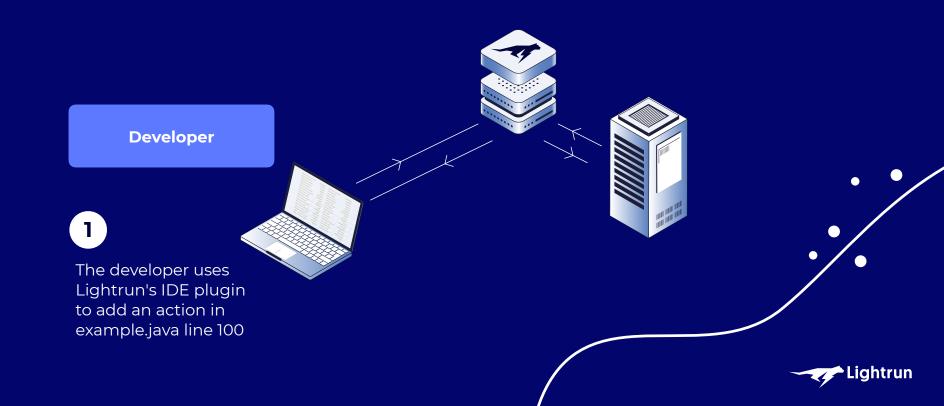


Continuous Observability?

Continuous Observability is a streamlined process of constantly asking new questions and getting immediate answers.



How it Works



How it Works

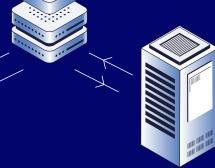
Management Server

2

Management Server sends request to the agent



The developer uses Lightrun's IDE plugin to add an action in example.java line 100





How it Works

Management Server

2

Management Server sends request to the agent Service Running with Lightrun's Agent

3

Developer

The developer uses Lightrun's IDE plugin to add an action in example.java line 100



Agent inserts the actions at the specific location at

runtime



How it Works

Management Server

2

Management Server sends request to the agent Service Running with Lightrun's Agent

Developer

The developer uses Lightrun's IDE plugin to add an action in example.java line 100



The data is transferred to the developer's IDE, through the Server



Agent inserts the actions at the specific location at runtime

3



It's Very Low Overhead?



It isn't an APM



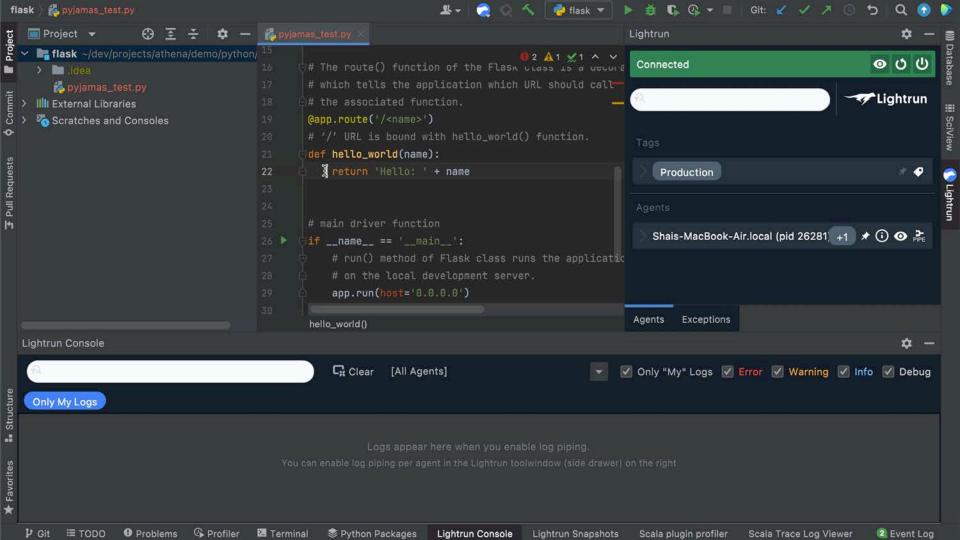
What if I Observe Something Central?

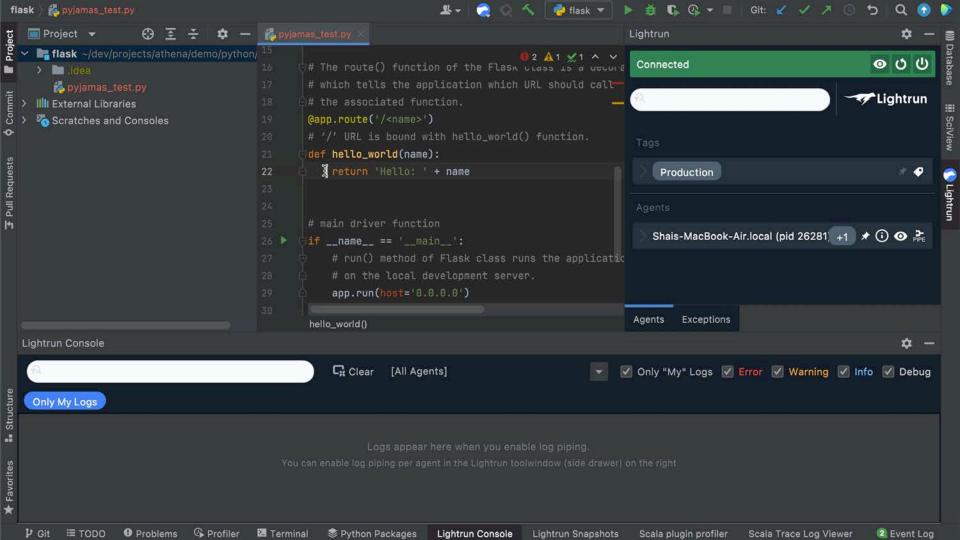


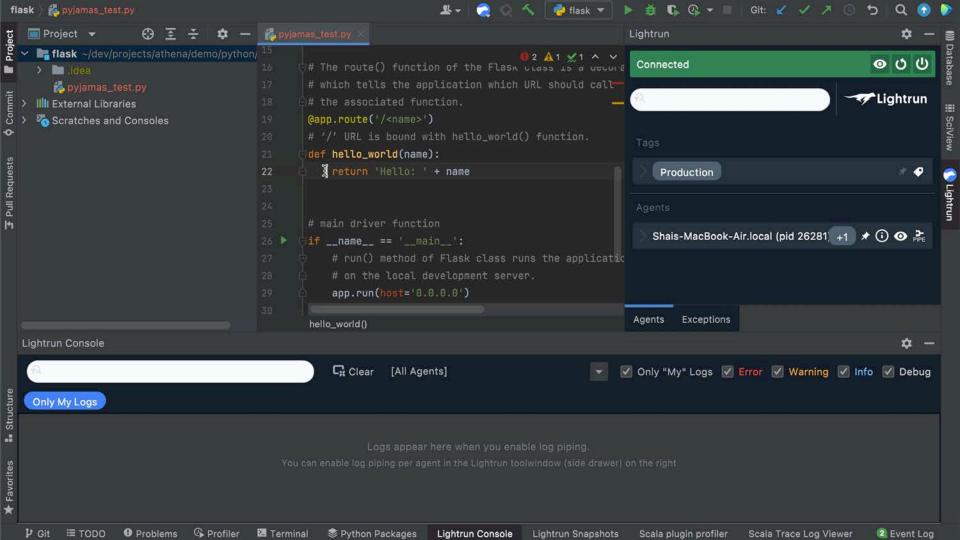


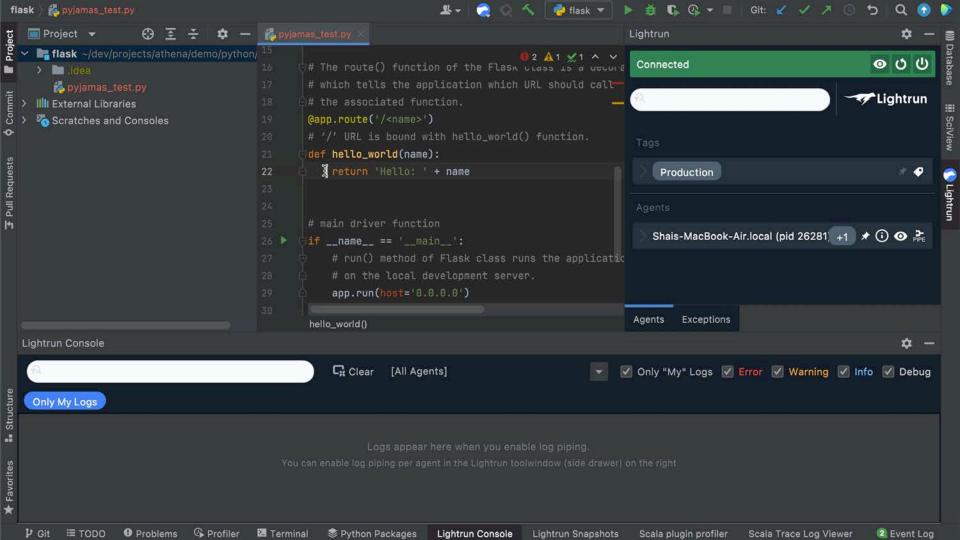
Demo

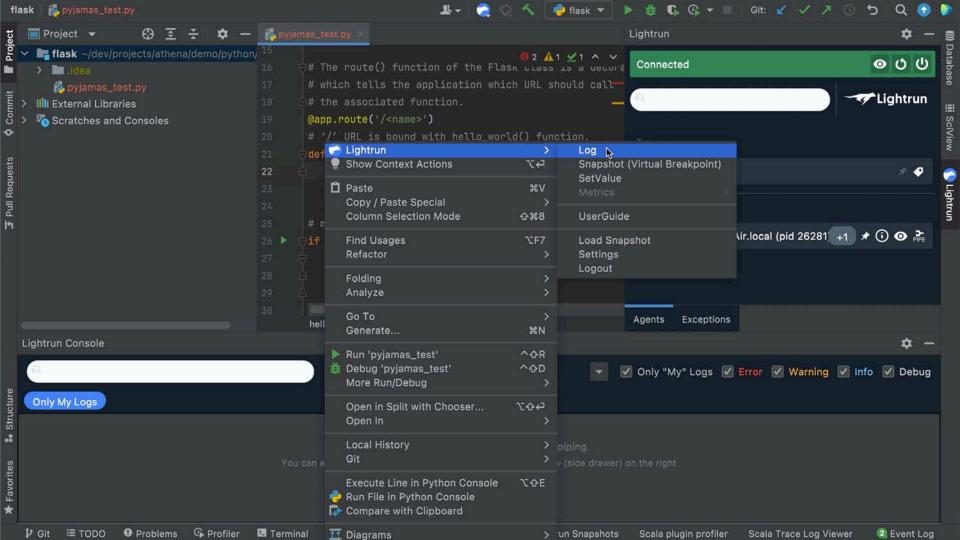


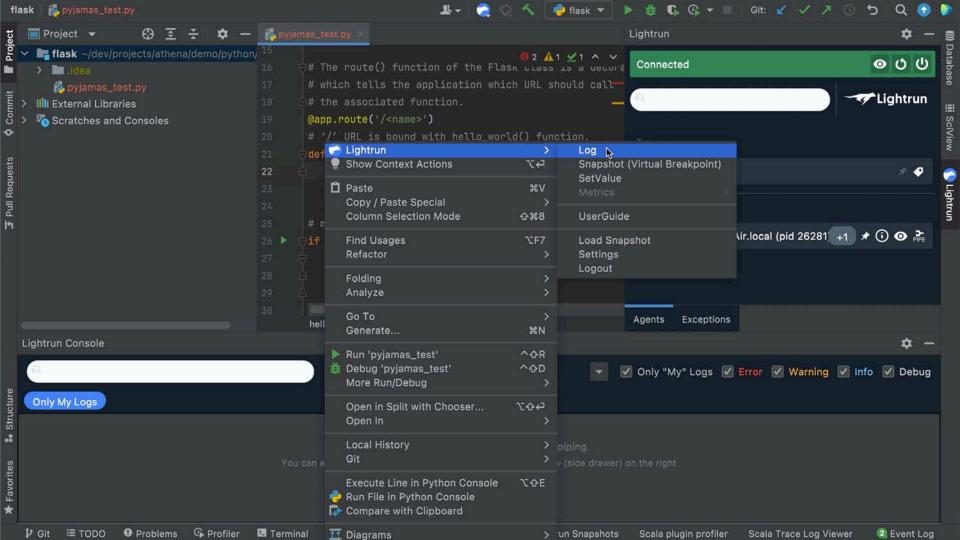


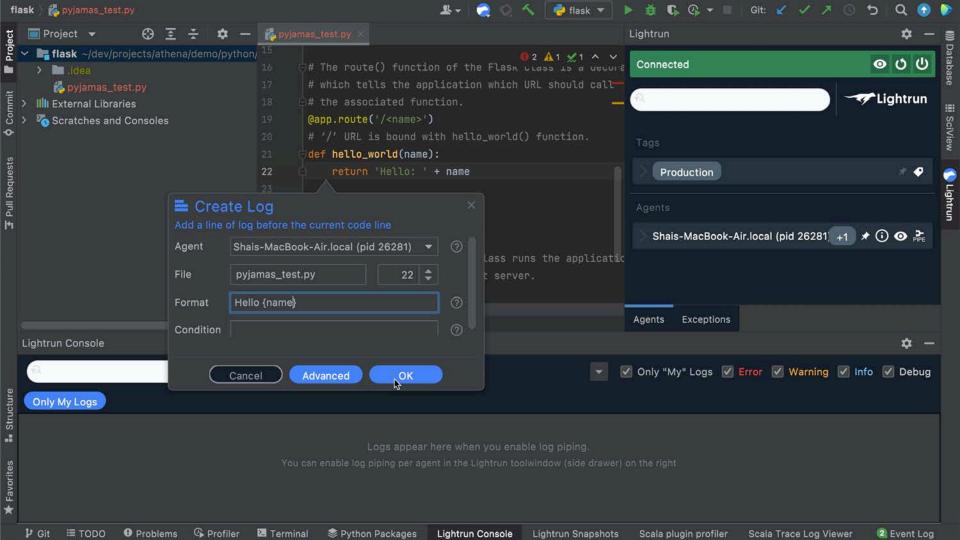


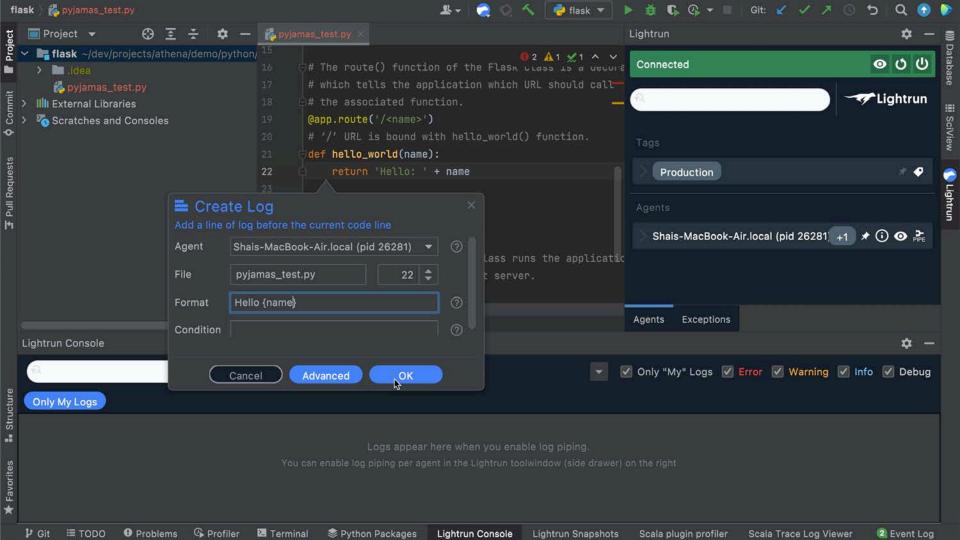


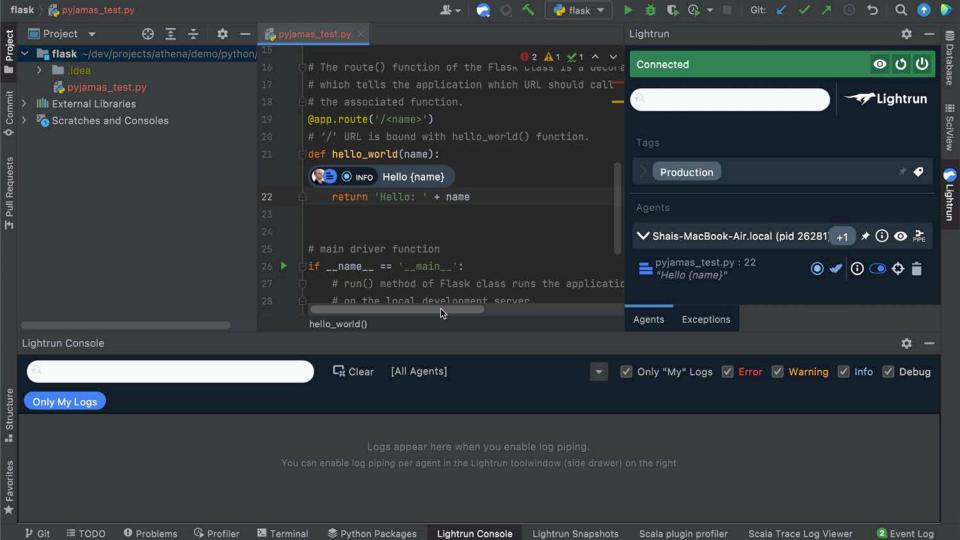


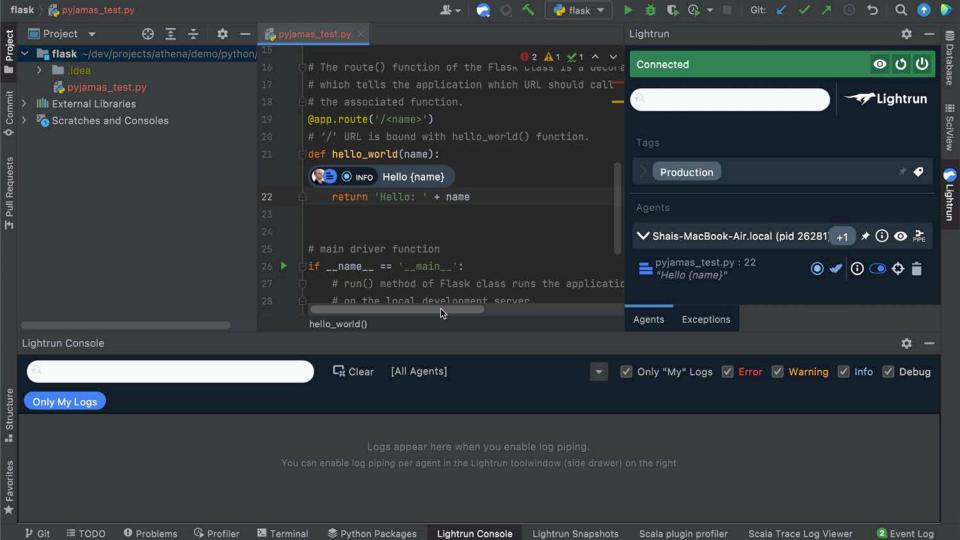


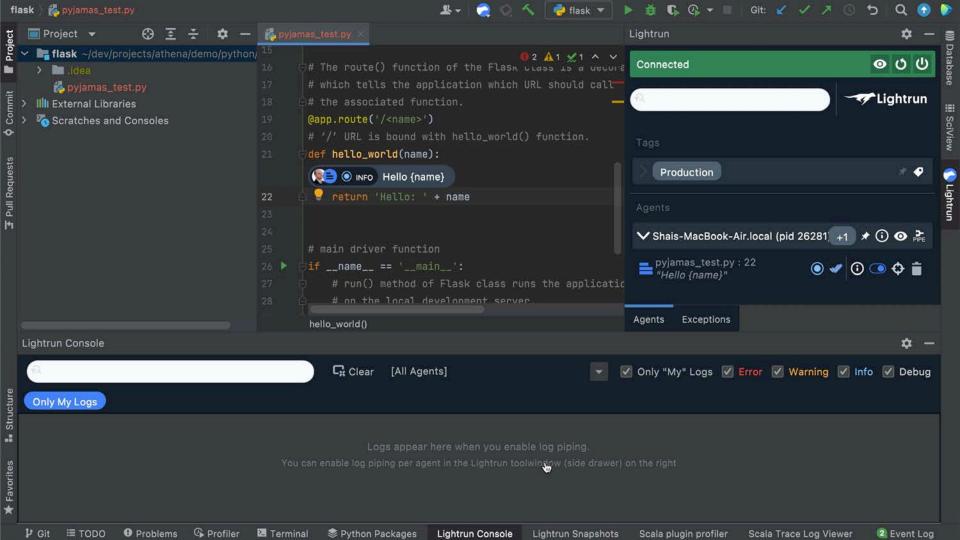


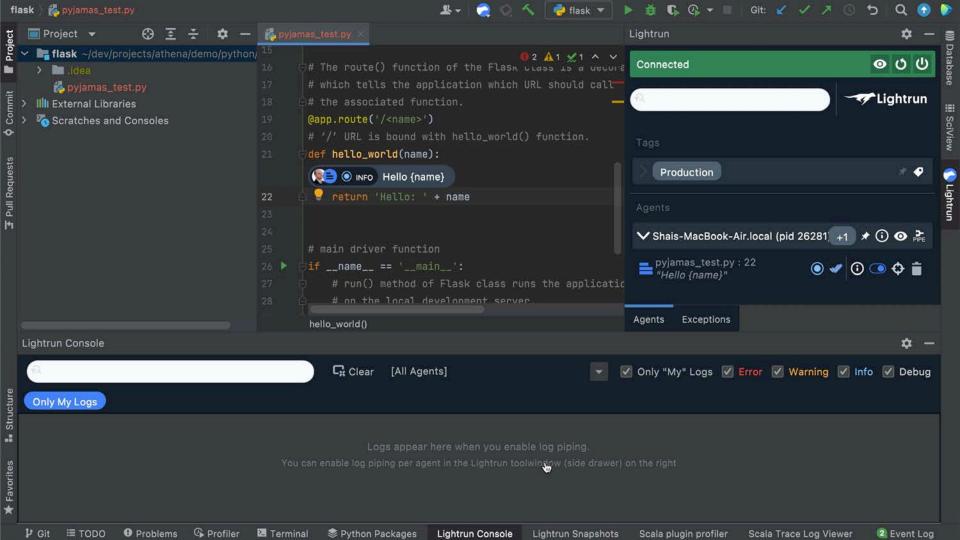


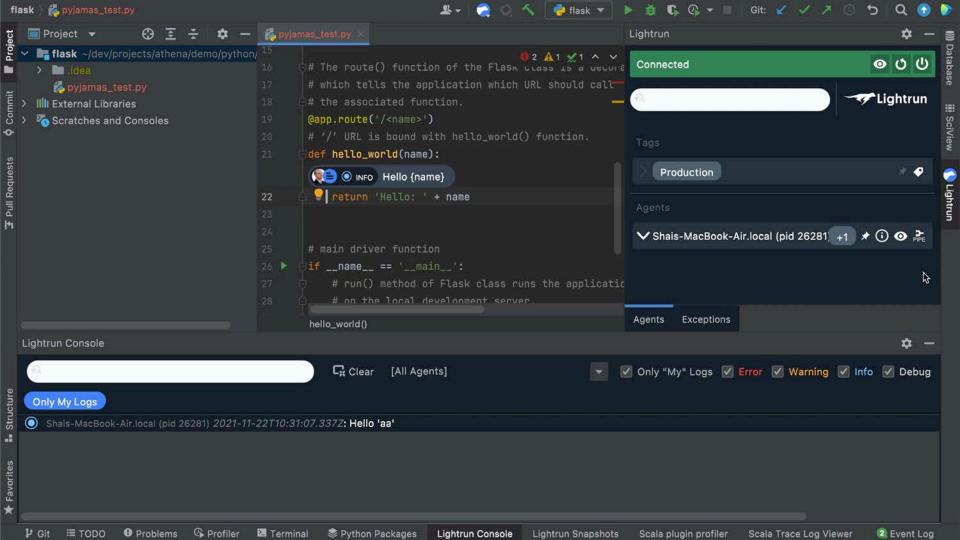


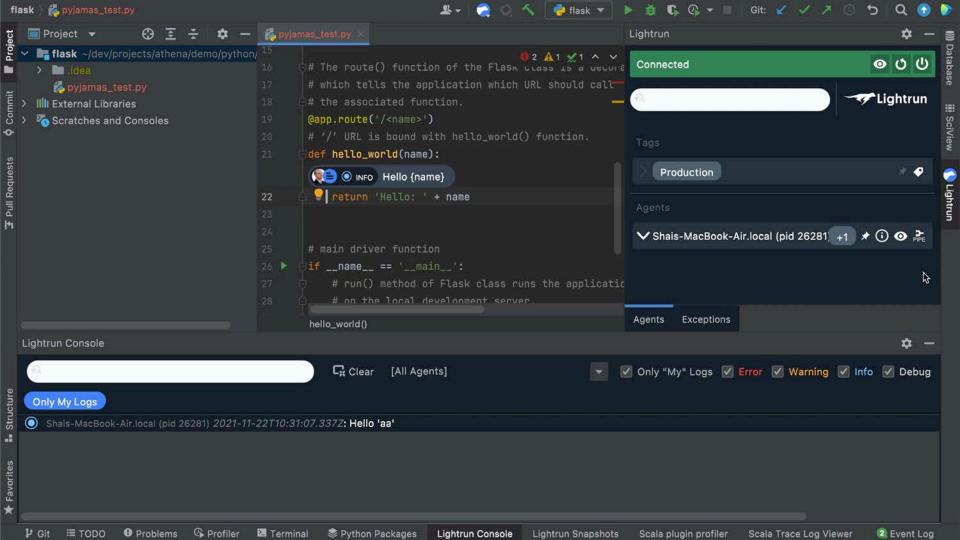


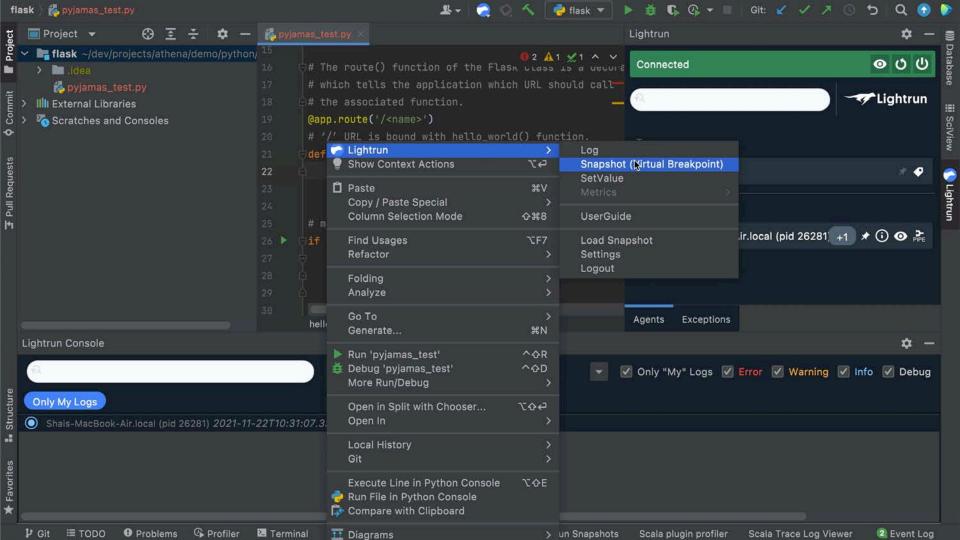


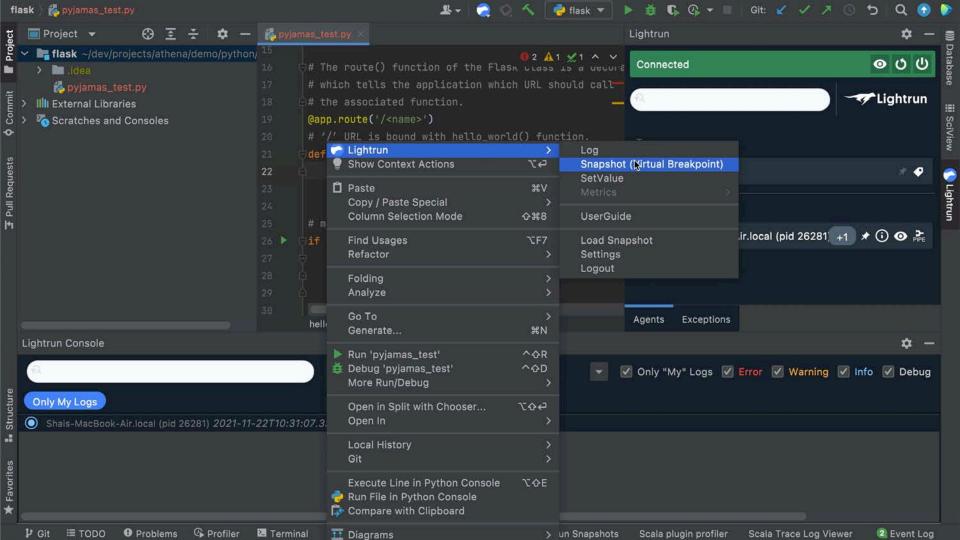


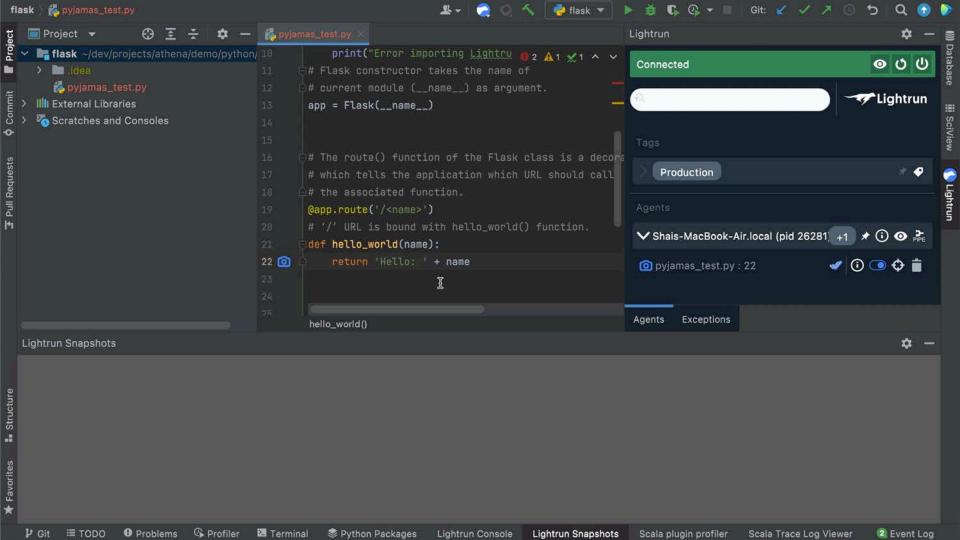


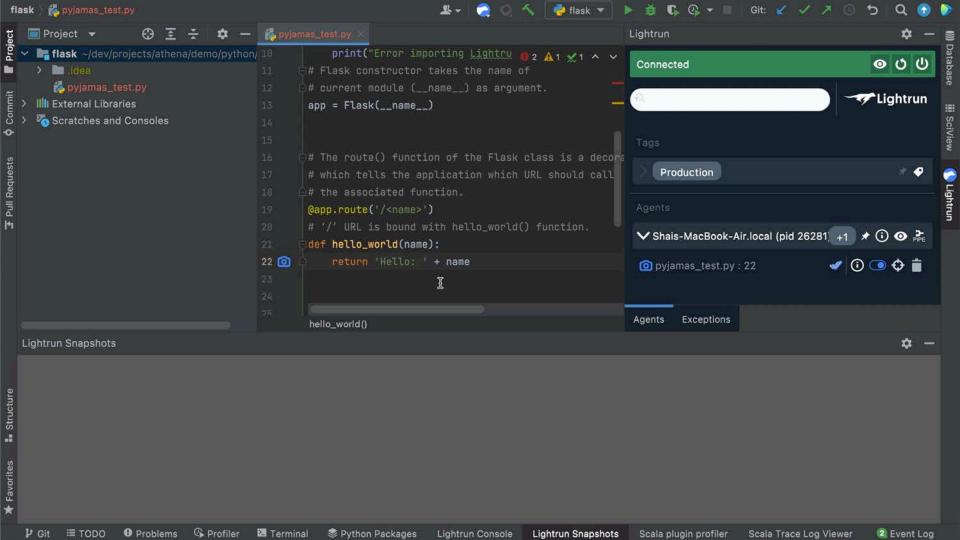


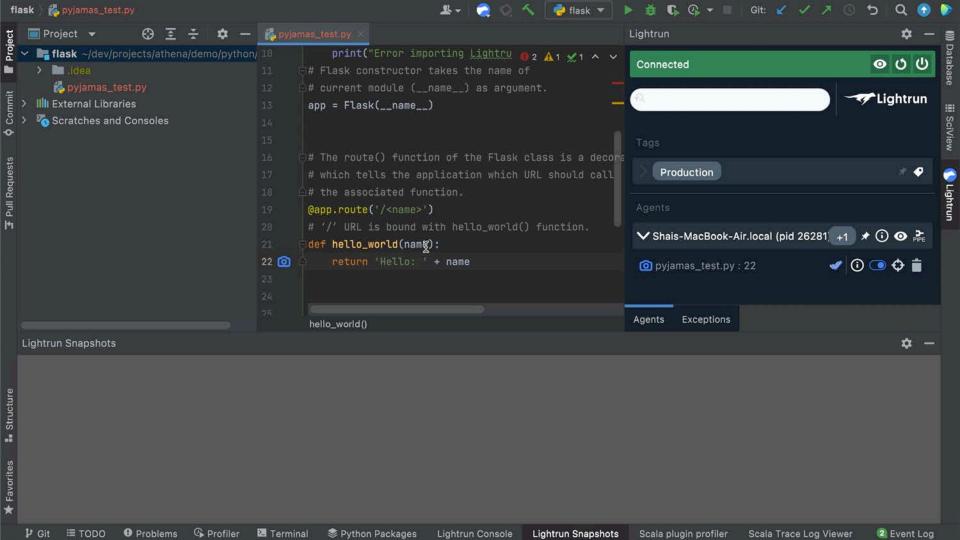


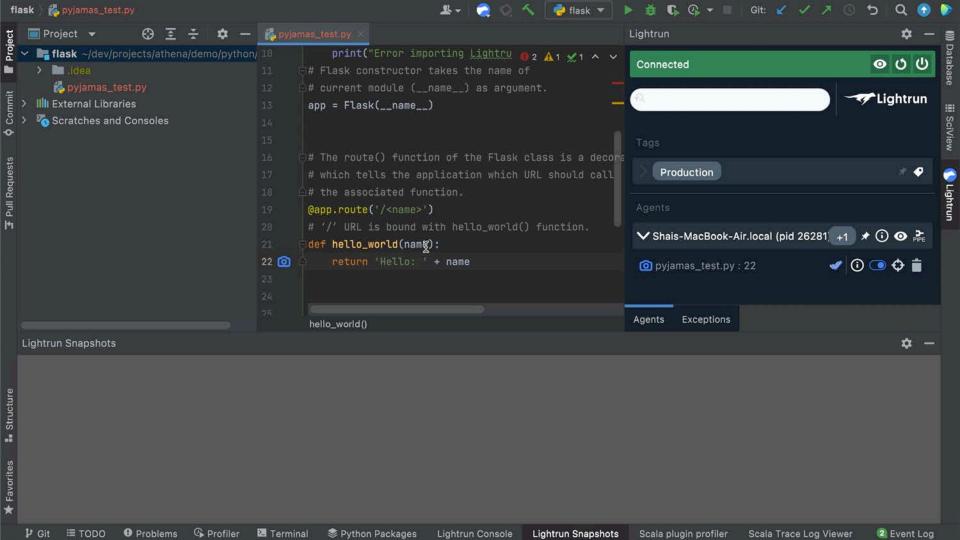


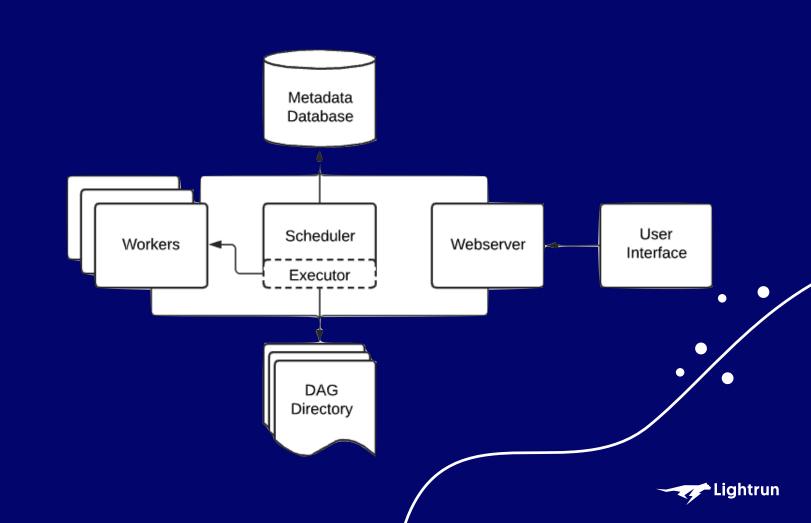


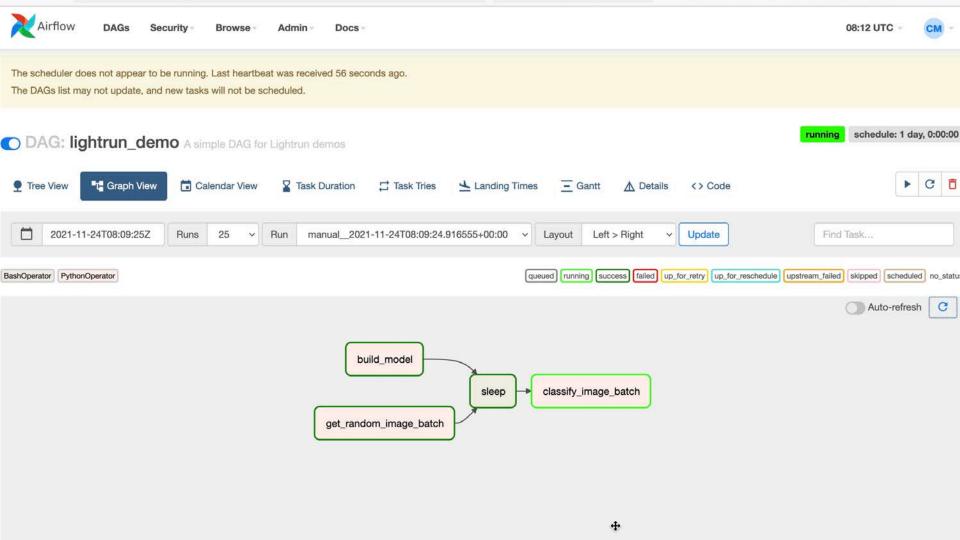


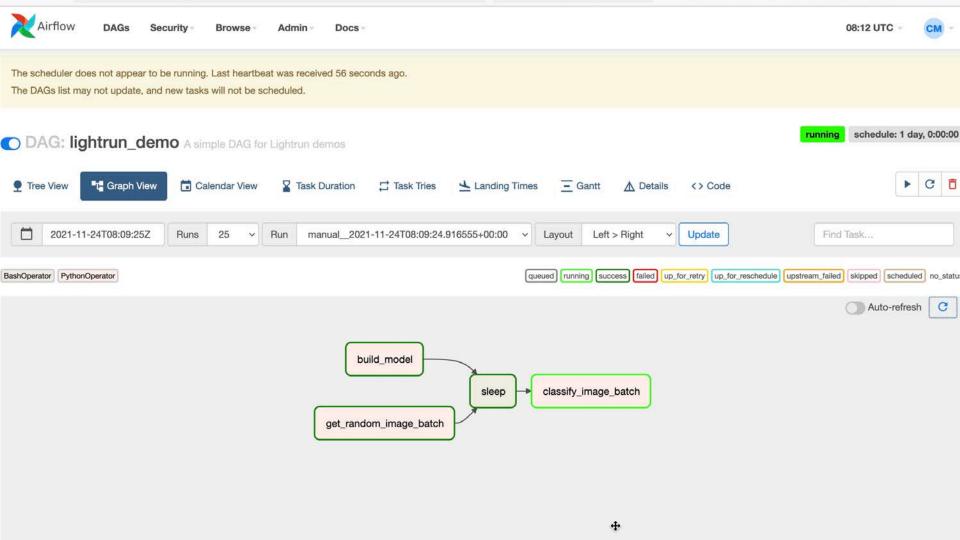












```
Lightrun
                                      Connected ....
                                                                  import random
                                                                  import time
                                                                  from datetime import timedelta
       Agents
                   Tags
                            Snapshots
                                                                  import tensorflow as tf
                                   1 Last us... T
                                                                  from airflow import DAG
\triangleleft
                                                                  from airflow.operators.bash import BashOperator
                                                                  from airflow.operators.python import PythonOperator
                                                                  from airflow.utils.dates import days_ago
                                                                  from lightrun.decorators import lightrun_airflow_task
                                                                  from mnist_classification_model import get_model
                                                                  # These args will get passed on to each operator.
                                                                  # You can override them on a per-task basis during operator initialization.
                                                                  default_args = {
                                                                      'owner': 'airflow',
                                                                      'depends_on_past': False,
                                                                      'email': ['airflow@example.com'],
                                                                      'email_on_failure': False,
                                                                      'email_on_retry': False,
                                                                      'retries': 1,
                                                                      'retry_delay': timedelta(minutes=5),
                                                                  def build model():
                                                                      get_model() # Builds the model if it isn't built
                                                                  def get_random_image_batch(ti):
                                                                      random.seed(5)
                                                                      mnist = tf.keras.datasets.mnist
                                                                      (x_train, y_train), (_, _) = mnist.load_data()
                                                                      random_image_batch = tf.convert_to_tensor([random.choice(x_train) for i in range(10)])
                                                                      # Pass the image batch to the next task as a python 3-D array (Tensors are not convertible to JSON)
                                                                      ti.xcom_push(key='random_image_batch', value=random_image_batch.numpy().tolist())
                                                                  @lightrun_airflow_task()
```

example.py > 1 classify_image_batch

47 Mef classify image hatch(ti).

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          Production
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3
                                                               # Pass the image batch to the next task as a python 3-D array (Tensors are not convertible to JSON)
                                Snapshot
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                                Custom Metric
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                                                      47
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                                                               image predictions = model.predict(images)
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                                                               for image prediction in image predictions:
                                                                   classified_numbers.append(tf.argmax(image_prediction).numpy())
                                                               return classified_numbers
                                                           with DAG('lightrun_demo',
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example.py > 😭 classify_image_batch > [@] image_batch

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                                                                                                                    Lightrun snapshot hit captured!
```

example.py > O classify_image_batch

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example py:47
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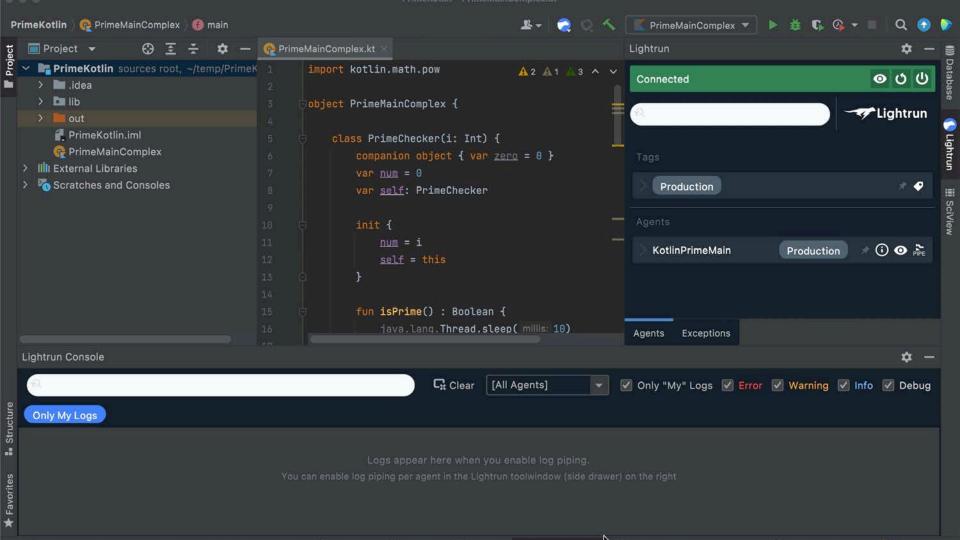
example.py > classify_image_batch

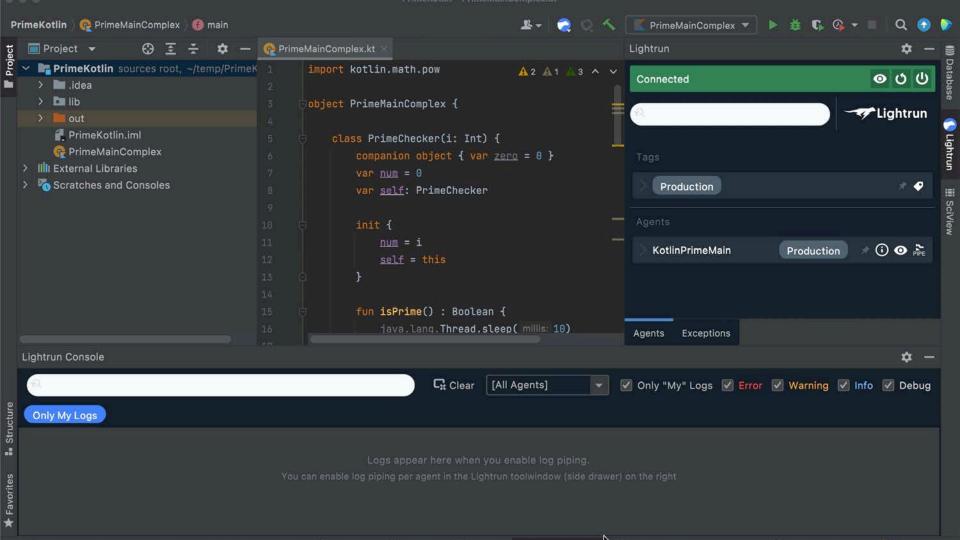
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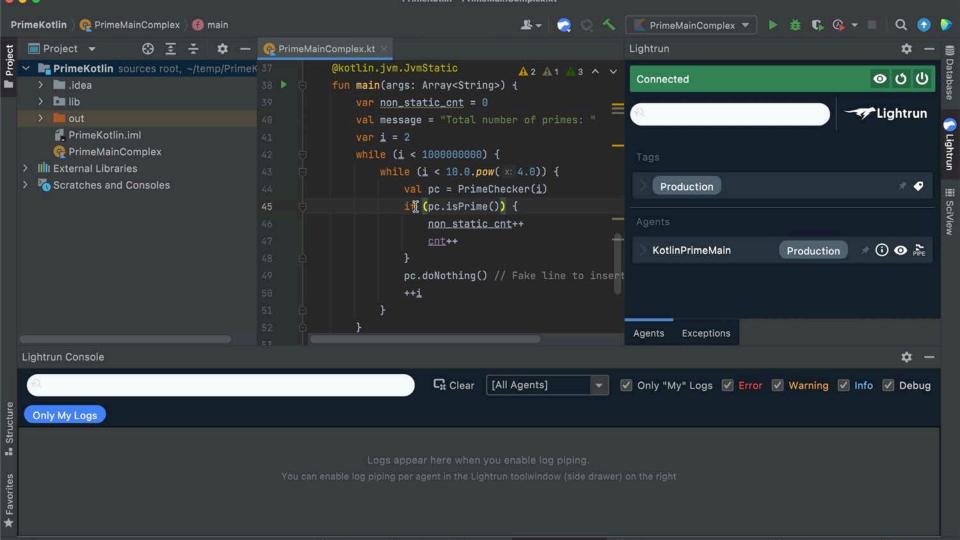
example.py > classify_image_batch

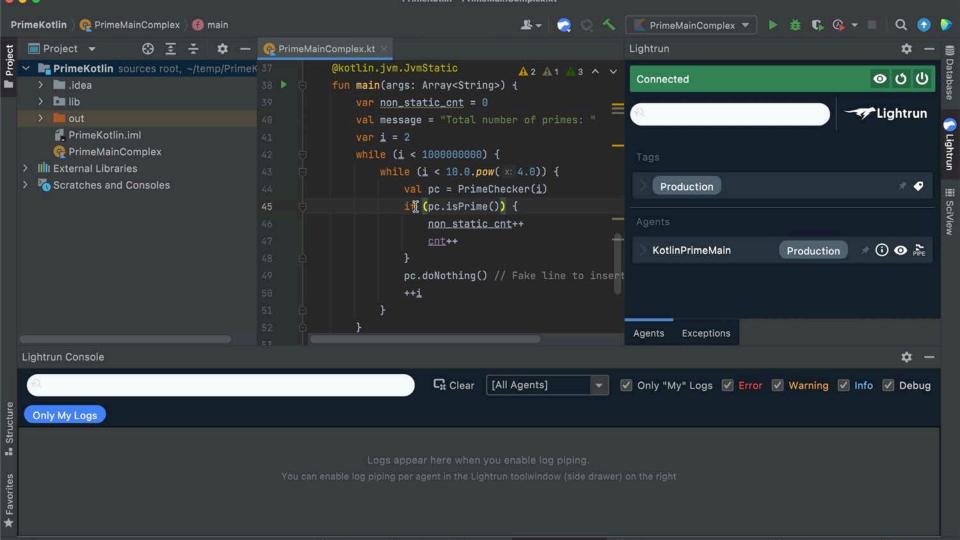
Demo: PrimeMain, Kotlin

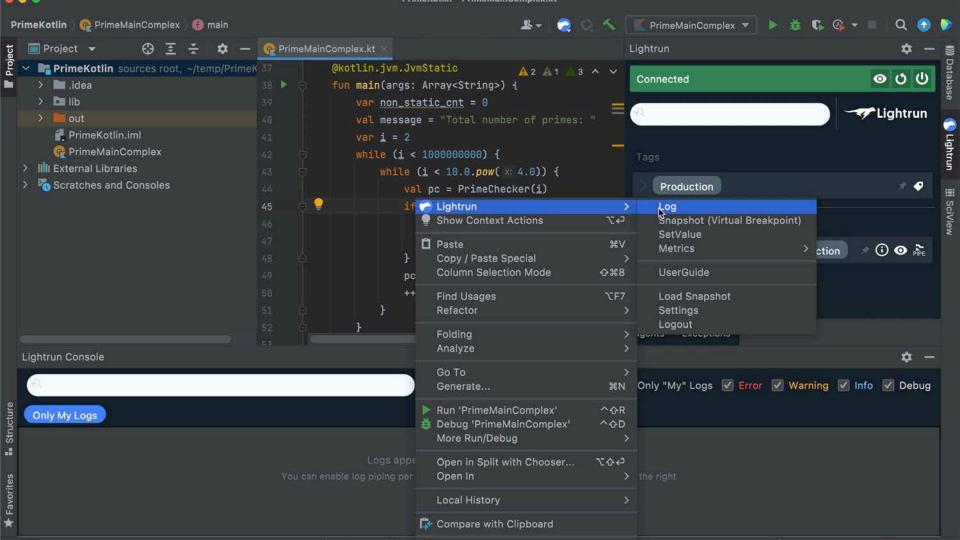


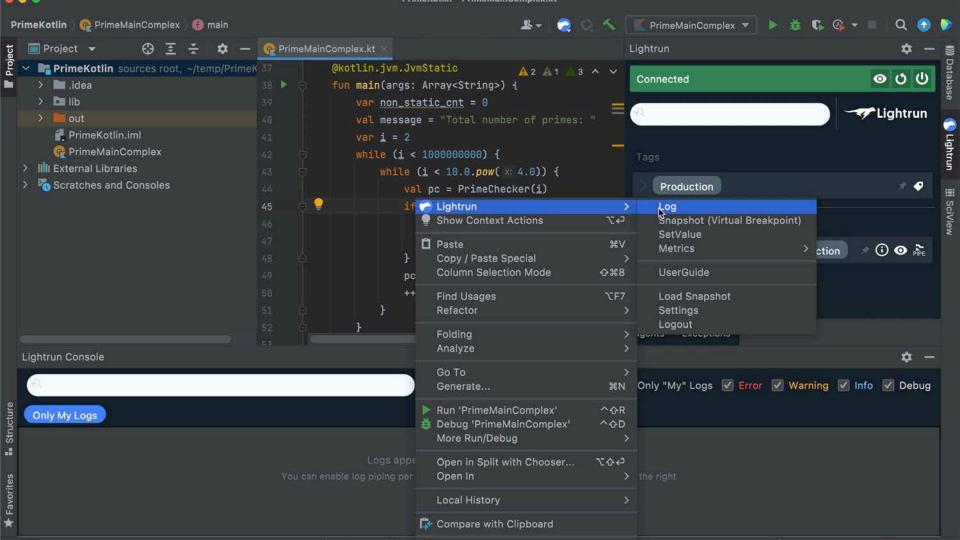


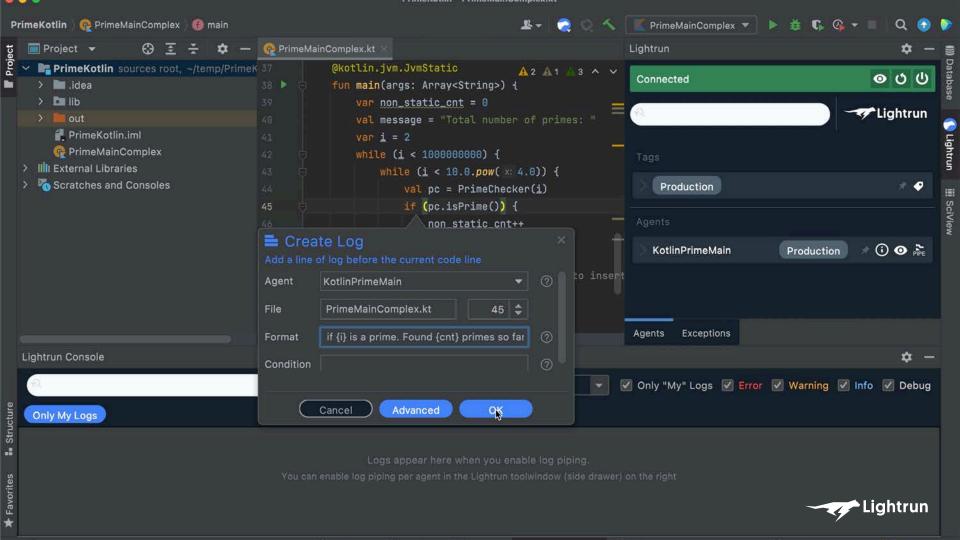


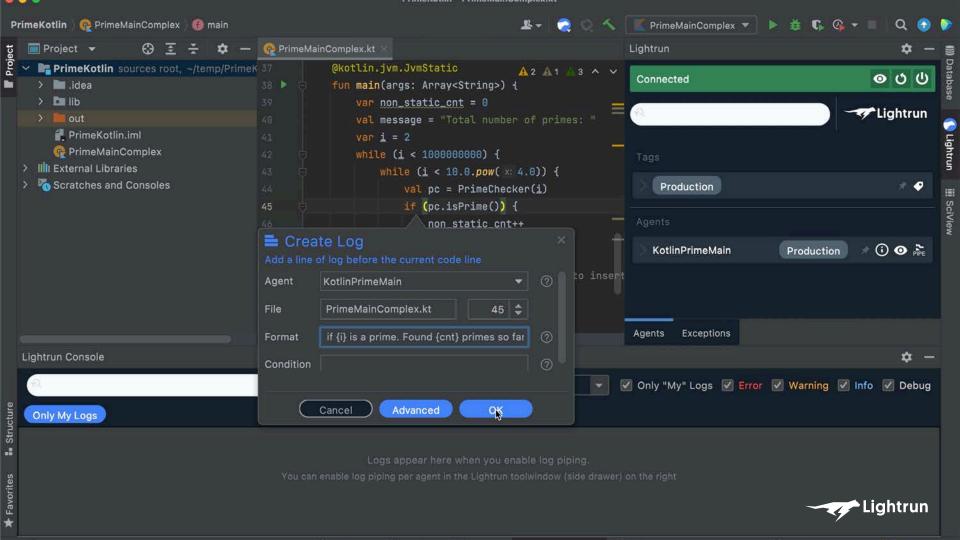


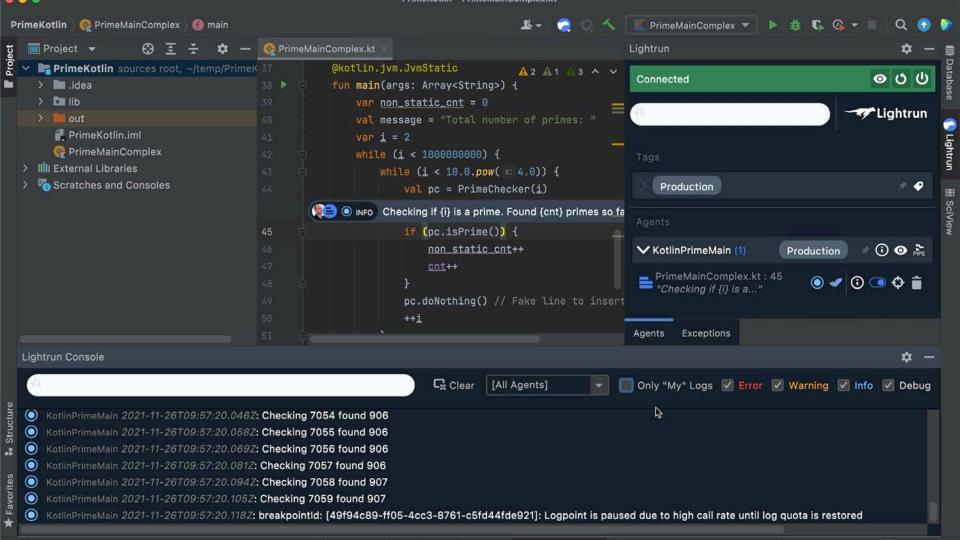


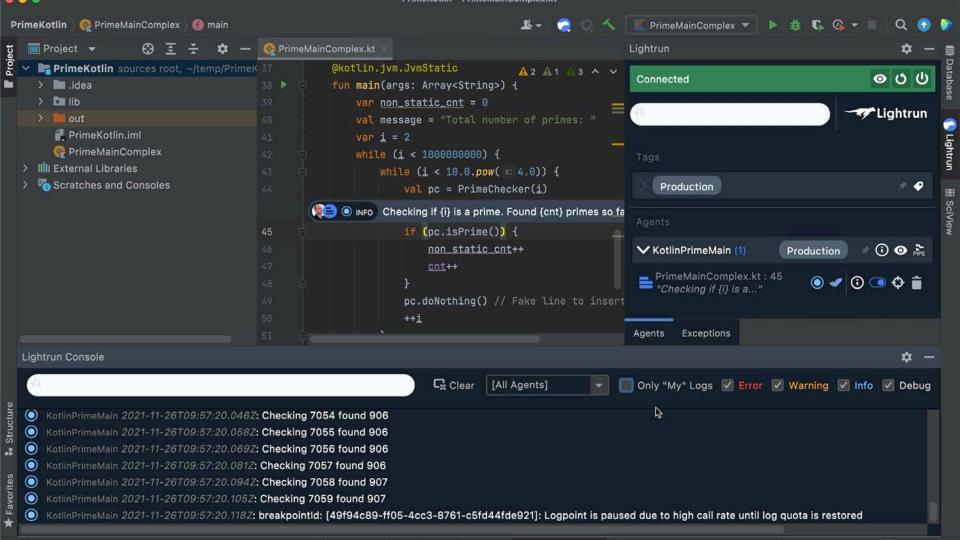


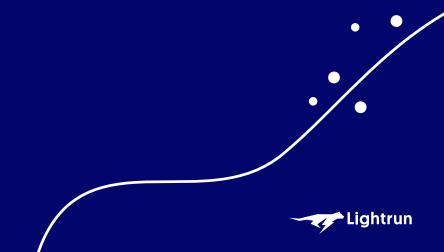




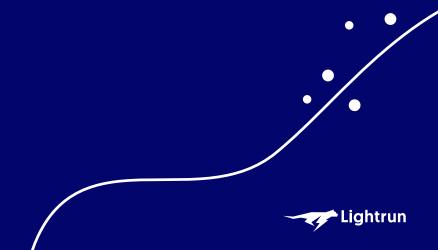






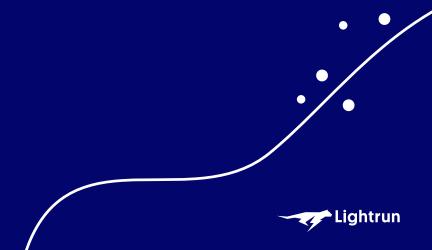








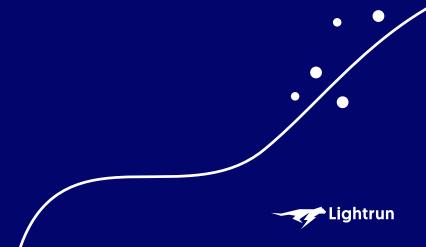




















Stability

Inserted Actions are emulated in a dedicated Sandbox to validate there are no side effects of the original flow and state of the process











Stability

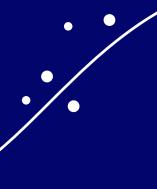
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Security

Authorization and authentication, integration with common IDPs















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Privacy

PII redaction and blacklisting of files / methods / members











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Environment agnostic

Operates on-prem / cloud, microservices, serverless













Questions?



Shai Almog Developer Advocate @ Lightrun

- y twitter.com/debugagent
- talktotheduck.dev
- github.com/shai-almog
- ✓ shaia@lightrun.com